

Second Order Equations

BCM ODEs

Defn:- A 2nd order linear differential equation is of the form:

$$\frac{d^2x}{dt^2} + p(t) \frac{dx}{dt} + q(t)x = f(t). \quad \dots (1)$$

where $p(t)$, $q(t)$ and $f(t)$ are given functions on $I \subseteq \mathbb{R}$.

We denote $\mathcal{L}(x) \equiv \frac{d^2x}{dt^2} + p(t) \frac{dx}{dt} + q(t)x$, then the ODE becomes:

$$\mathcal{L}(x) = f(t). \quad \dots (1)$$

\Rightarrow The eqn (1) is called homogeneous if $f(t) = 0 \forall t \in I$, else, it is called non-homogeneous.

Existence & Uniqueness Theorem :- Let, p, q, f be continuous

in a compact interval $I \subseteq \mathbb{R}$. For any $t_0 \in I$ and constants α_1, α_2 , \exists a unique solution for the IVP:

$$\begin{cases} \mathcal{L}(x) = f(t) \\ x(t_0) = \alpha_1, x'(t_0) = \alpha_2 \end{cases}$$

Defn:- An operator $\mathcal{L} \equiv D^n + a_{n-1}(t)D^{n-1} + \dots + a_1D + a_0$ is said to be a linear operator if for any n times differentiable functions y_1 & y_2 and constants c_1, c_2 , we have

$$\mathcal{L}(c_1 y_1(t) + c_2 y_2(t)) = c_1 \mathcal{L}(y_1) + c_2 \mathcal{L}(y_2). \quad \text{where,}$$

$$D \equiv \frac{d}{dt}$$

(Superposition Principle) Theorem 8.

Let, $\phi_1(t)$ and $\phi_2(t)$ are solutions for $\mathcal{L}(x) = f_1$ and $\mathcal{L}(x) = f_2$ respectively.

Then, $\alpha_1 \phi_1(t) + \alpha_2 \phi_2(t)$ is a solution of

$$\mathcal{L}(x) = \alpha_1 f_1 + \alpha_2 f_2, \quad \alpha_1, \alpha_2 \in \mathbb{R}.$$

The Superposition principle is NOT true for non-linear equations:

ExM:

$$x^3 y'' - y y' = 0.$$

$y_1 = 1$ and $y_2 = x^2$ are two solutions of the ODE.

But, their linear combination $4 + 3x^2$ is not a sol \underline{n} .

NOTE :- If $f_1 = f_2 = 0$ in Thm 8., then $C_1 \phi_1 + C_2 \phi_2$ is also a sol \underline{n} of $\mathcal{L}(x) = 0$.

This is not true for non-homogeneous eq \underline{n} s:

ExM :- $y'' - 9y = 18.$

$y_1 = 4e^{3x} - 2$ and $y_2 = e^{3x} - 2$ are two sol \underline{n} s.

But, their sum $5e^{3x} - 4$ is not a sol \underline{n} of $y'' - 9y = 18.$

Defn :- The functions f_1, f_2, \dots, f_n are said to be linearly dependent on I , if \exists constants C_1, C_2, \dots, C_n , not all zeros, such that

$$C_1 f_1(x) + C_2 f_2(x) + \dots + C_n f_n(x) \equiv 0 \quad \forall x \in I.$$

The set of functions is said to be linearly independent if it is not linear dependent.

ExM :- $f_1 = 1, f_2 = x, f_3 = x^2$ are L.I.

ExM :- $f_1(x) = \begin{cases} 0, & x \in [0, \frac{1}{2}) \\ x, & x \in [\frac{1}{2}, 1] \end{cases}$, $f_2(x) = \begin{cases} 0, & x = 0 \\ x^2, & \text{else} \end{cases}$, $f_3(x) = (1+x)$

are L.I.

Exm. $f_1 = x$, $f_2 = 2x$, $f_3(x) = x^2$ are L.D.

Exm: $f_1 = x$, $f_2 = |x|$ are L.I.

Definition :- The Wronskian of two differentiable functions $\phi_1(x)$ & $\phi_2(x)$ on an interval I is defined by

$$W(\phi_1, \phi_2; x) = \begin{vmatrix} \phi_1(x) & \phi_2(x) \\ \phi_1'(x) & \phi_2'(x) \end{vmatrix} = \phi_1 \phi_2' - \phi_2 \phi_1'$$

Theorem 9. Let, ϕ_1 & ϕ_2 be two solutions of $\mathcal{L}(y) = 0$ on I .

Then, ϕ_1 & ϕ_2 are L.I. iff $W(\phi_1, \phi_2; x) \neq 0 \forall x \in I$.

Proof :- Let, $W(\phi_1, \phi_2; x) \neq 0 \forall x \in I$.

Consider $c_1 \phi_1(x) + c_2 \phi_2(x) = 0 \quad \forall x \in I$.

So, we have,

$$c_1 \phi_1'(x) + c_2 \phi_2'(x) = 0 \quad \forall x \in I$$

Let, $x_0 \in I$, then

$$\phi_1(x_0) c_1 + \phi_2(x_0) c_2 = 0$$

$$\phi_1'(x_0) c_1 + \phi_2'(x_0) c_2 = 0$$

Now, since $W(\phi_1, \phi_2; x_0) \neq 0$, so by Cramer's Rule, the homogeneous system has unique soln, i.e.

$$c_1 = 0 = c_2$$

Hence, ϕ_1 & ϕ_2 are L.I.

Conversely, let, ϕ_1, ϕ_2 are L.I. in I .

If possible, let, $W(\phi_1, \phi_2; x_0) = 0$ for $x_0 \in I$.

Then, the system

$$\phi_1(x_0) c_1 + \phi_2(x_0) c_2 = 0$$

$$\phi_1'(x_0) c_1 + \phi_2'(x_0) c_2 = 0$$

has a non-trivial solution (c_1^*, c_2^*) . i.e.

$$|c_1^*| + |c_2^*| \neq 0$$

Consider, $X(x) = c_1^* \phi_1(x) + c_2^* \phi_2(x)$. and the

IVP:

$$\mathcal{L}(y) = 0, \quad y(x_0) = 0, \quad y'(x_0) = 0.$$

Then, clearly $X(x)$ is a solution of the IVP.

Also, $y(x) \equiv 0$ is another solution. But, by uniqueness,

$$X(x) \equiv 0 \quad \forall x \in I.$$

$$\Rightarrow c_1^* \phi_1(x) + c_2^* \phi_2(x) = 0 \quad \forall x \in I.$$

$$\Rightarrow \phi_1, \phi_2 \text{ are L.D., a contradiction.}$$

Therefore, $W(\phi_1, \phi_2; x) \neq 0 \quad \forall x \in I$.

NOTE :- $W(\phi_1, \phi_2; x) \neq 0 \quad \forall x \in I \Rightarrow \phi_1, \phi_2$ are L.I.

but, ϕ_1, ϕ_2 are LI $\nRightarrow W(\phi_1, \phi_2; x) \neq 0$. To satisfy

Theorem 9, ϕ_1, ϕ_2 have to solve $\mathcal{L}(y) = 0$.

Exm: $\phi_1(x) = x, \quad \phi_2(x) = x^2, \quad x \in [-1, 1]$.

We know ϕ_1, ϕ_2 are L.I. But,

$$W(\phi_1, \phi_2; 0) = \begin{vmatrix} x & x^2 \\ 1 & 2x \end{vmatrix} \Big|_{x=0} = 0.$$

Theorem 10. (Abel Theorem)

Let, ϕ_1 & ϕ_2 be two solutions of the diff. eqn $\mathcal{L}(y) = 0$. Then the Wronskian satisfies a 1st order differential equation.

Proof :- Let, ϕ_1 & ϕ_2 be two solutions of

$$y''(x) + p(x)y'(x) + q(x)y(x) = 0 \quad \dots (1)$$

We have

$$W(\phi_1, \phi_2; x) = \phi_1 \phi_2' - \phi_2 \phi_1'$$

$$\begin{aligned} \text{So, } \frac{dW}{dx} &= \phi_1 \phi_2'' - \phi_2 \phi_1'' \\ &= \phi_1(x) [-p(x)\phi_2'(x) - q(x)\phi_2(x)] - \phi_2(x) [-p(x)\phi_1'(x) - q(x)\phi_1(x)] \end{aligned}$$

$$= p(x) [\phi_2 \phi_1' - \phi_1 \phi_2']$$

$$= -p(x) W(\phi_1, \phi_2; x)$$

$$\therefore \frac{dW}{dx} + p(x)W = 0 \quad \dots (11)$$

So, $W(x)$ satisfies the ODE (11).

Theorem 11. Let, $\phi_1(x)$ & $\phi_2(x)$ be two solutions of $L(y) = 0$ on I . Then, $W(\phi_1, \phi_2; x)$ is either identically zero or is never zero on I .

Proof :- We have from Theorem 10,

$$W' + p(x)W = 0$$

$$\Rightarrow \frac{d}{dx} \left[W(x) \exp\left(\int_{x_0}^x p(s) ds\right) \right] = 0$$

$$\Rightarrow W(x) \exp\left(\int_{x_0}^x p(s) ds\right) - W(x_0) = 0,$$

after integrating over x_0 to x ,

$$\Rightarrow W(\phi_1, \phi_2; x) = W(x_0) \exp\left(-\int_{x_0}^x p(s) ds\right)$$

We now have two possibilities:

$$W(x_0) = 0 \quad \text{and} \quad W(x_0) \neq 0.$$

Accordingly, $W(\phi_1, \phi_2; x) = 0$ or $W(\phi_1, \phi_2; x) \neq 0$ on I .

NOTE :- Thm 11 is not true if ϕ_1 & ϕ_2 are not solutions to some $L(y) = 0$.

Exm: $\phi_1(x) = \sin x$, $\phi_2(x) = x \sin x$, $W(\phi_1, \phi_2; x) = \sin^2 x$

Theorem 12. Let, ϕ_1, ϕ_2 be two L.I. solutions of $\mathcal{L}(y) = 0$ on I . Then every solution of $\mathcal{L}(y) = 0$ can be expressed uniquely as

$$\phi(x) = c_1 \phi_1(x) + c_2 \phi_2(x), \quad \forall x \in I.$$

Proof:- Let, $\phi(x)$ be any solution of $\mathcal{L}(y) = 0$ on I .

Let, $x_0 \in I$ and $\phi(x_0) = \alpha, \phi'(x_0) = \beta$.

Since ϕ_1 and ϕ_2 are L.I., $W(\phi_1, \phi_2; x_0) \neq 0$.

So, the system of equations:

$$\phi_1(x_0)c_1 + \phi_2(x_0)c_2 = \alpha$$

$$\phi_1'(x_0)c_1 + \phi_2'(x_0)c_2 = \beta$$

has a unique solution (c_1^*, c_2^*) , by Cramer's Rule.

Consider $\psi(x) = c_1^* \phi_1(x) + c_2^* \phi_2(x)$.

Clearly $\psi(x)$ is a solution of

$$\mathcal{L}(y) = 0; \quad y(x_0) = \alpha, \quad y'(x_0) = \beta$$

But, by assumption $\phi(x)$ is another sol~~u~~tion of the ODE.

Hence by uniqueness,

$$\phi(x) = \psi(x)$$

$$= c_1^* \phi_1(x) + c_2^* \phi_2(x) \quad \forall x \in I.$$

This completes the theorem.

Defn:- Any two L.I. solutions ϕ_1, ϕ_2 of $\mathcal{L}(y) = 0$ form a basis or fundamental set of solutions on I .

The family of solutions $c_1 \phi_1(x) + c_2 \phi_2(x)$, which contains all solutions, is called the general solution of $\mathcal{L}(y) = 0$.

NOTE:- Fundamental Set is NOT unique for $\mathcal{L}(y) = 0$.

EXM: $\{1, x\}$ and $\{2, 2x\}$ both are basis to $y'' = 0$.

Non-homogeneous ODEs :-

$$\mathcal{L}(y) := y'' + p(x)y' + q(x)y = f(x).$$

$$\text{i.e. } \mathcal{L}(y) = f(x). \quad \dots \dots (II)$$

Problems :-

1. Show that $y_1 = e^t$, $y_2 = e^{-2t}$ are fundamental solutions to $y'' + y' - 2y = 0$.

2. Show that, $y_1(t) = \sin t$ & $y_2(t) = t \sin(t)$ are L.I.

3. Find the Wronskian of ~~the~~ two solutions of the eqn: $t^2 y'' - (t+2)t y' + (t+2)y = 0$, $t > 0$, given that, $W(1) = e$.
[Ans: $W(t) = t^2 e^t$]

— Any solution of (II) of the form $y = y_p$ is called a particular solution. Let, S_p be the set of all solutions of (II).

Lemma 4. Let, ϕ_1, ϕ_2 be two L.I solutions of $\mathcal{L}(y) = 0$.

Then for the equation $\mathcal{L}(y) = f(x)$, the following are equivalent:

a) $y \in S_p$

b) $y = c_1 \phi_1(x) + c_2 \phi_2(x) + y_p$; for $\underset{\text{some}}{y_p} \in S_p$.

Proof :- (b) \Rightarrow (a)

$$\mathcal{L}(y) = \mathcal{L}(c_1 \phi_1 + c_2 \phi_2) + \mathcal{L}(y_p)$$

$$= 0 + f(x) = f(x).$$

So, $y \in S_p$.

(a) \Rightarrow (b). Let, $y \in S_p$ and $y_p \in S_p$ be a particular solution.

Then

$$\mathcal{L}(y - y_p) = \mathcal{L}(y) - \mathcal{L}(y_p)$$

$$= 0$$

So, by Theorem 12, $y - y_p$ has the form:

$$y - y_p = c_1 \phi_1 + c_2 \phi_2$$

$$\Rightarrow \underline{y = c_1 \phi_1 + c_2 \phi_2 + y_p}$$

\Rightarrow The general solution of $\mathcal{L}(y) = 0$ is known as complementary solution, denoted by y_c .

That is,

$$y_c(x) = c_1 \phi_1(x) + c_2 \phi_2(x).$$

Therefore, the general solution of $\mathcal{L}(y) = f$ may be written as:

$$y(x) = y_c(x) + y_p(x).$$

Theorem 13 (Method of Variation of Parameters)

A particular solution of $y'' + p(x)y' + q(x)y = f(x) \dots (1)$

is given by

$$y_p(x) = \int \frac{\phi_1(t)\phi_2(x) - \phi_1(x)\phi_2(t)}{W(\phi_1, \phi_2; t)} f(t) dt$$

where $\{\phi_1, \phi_2\}$ is a fundamental set of $\mathcal{L}(y) = 0$ in I .

Proof: - We are looking for solution of (1) of the form

$$y_p(x) = c_1(x)\phi_1(x) + c_2(x)\phi_2(x).$$

where $c_1(x)$ and $c_2(x)$ are two unknown function.

Since y_p is a solution to (1),

we have,

$$2(C_1'\phi_1' + C_2'\phi_2') + C_1''\phi_1 + C_2''\phi_2 + p(x)[C_1'\phi_1 + C_2'\phi_2] \\ + q(x)(C_1\phi_1'' + p(x)C_1\phi_1' + q(x)C_1\phi_1) + C_2(\phi_2'' + p(x)\phi_2' + q(x)\phi_2)$$

Since $\phi_1(x)$ & $\phi_2(x)$ are solutions to $L(y) = 0$, $= f(x)$.
We have further

$$2(C_1'\phi_1' + C_2'\phi_2') + C_1''\phi_1 + C_2''\phi_2 + p(x)\{C_1'\phi_1 + C_2'\phi_2\} = f(x) \quad \dots (iii)$$

To find $C_1(x)$ and $C_2(x)$, we need two equations in C_1 & C_2 :

Consider the first equation as:

$$C_1'\phi_1 + C_2'\phi_2 = 0 \quad \dots (iv), \quad \forall x \in I.$$

So, (iii) \Rightarrow

$$2(C_1'\phi_1' + C_2'\phi_2') + C_1''\phi_1 + C_2''\phi_2 = f(x).$$

Now from (iv) \Rightarrow

$$C_1'\phi_1' + C_2'\phi_2' = -C_1''\phi_1 - C_2''\phi_2$$

Therefore

$$C_1'\phi_1' + C_2'\phi_2' = f(x) \quad \dots (v)$$

So, (iv) & (v) are two equations in C_1 & C_2 . (or C_1', C_2')

Now, since $W(\phi_1, \phi_2; x) \neq 0$, (iv) & (v) are solvable in C_1', C_2' .

By Cramer's Rule,

$$C_1'(x) = -\frac{\phi_2(x)f(x)}{W(\phi_1, \phi_2; x)}, \quad C_2'(x) = \frac{\phi_1(x)f(x)}{W(\phi_1, \phi_2; x)}$$

Therefore,

$$C_1(x) = -\int \frac{\phi_2(t)f(t)}{W(\phi_1, \phi_2; t)} dt, \quad C_2(x) = \int \frac{\phi_1(t)f(t)}{W(\phi_1, \phi_2; t)} dt.$$

Thus,

$$y_p(x) = \int \frac{\phi_1(t)\phi_2(x) - \phi_1(x)\phi_2(t)}{W(\phi_1, \phi_2; t)} f(t) dt.$$

EXM:- $y'' + y = \tan x$.

Note that a fundamental solution is $\{\cos x, \sin x\}$.

Now, $W(\phi_1, \phi_2; x) = \begin{vmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{vmatrix} = 1$.

$$y_p(x) = C_1(x) \cos x + C_2(x) \sin x$$

$$y_p(x) = \int \frac{\cos t \sin x - \cos x \sin t}{1} \cdot \tan t \, dt$$

$$= \sin x \int \cos t \tan t \, dt - \cos x \int \tan t \sin t \, dt$$

$$= -\sin x \cos x - \cos x \int \sin^2 t \sec t \, dt$$

$$= -\sin x \cos x - \cos x \int \sec t \, dt + \cos x \int \cos t \, dt$$

$$= -\sin x \cos x + \cos x \sin x - \cos x \ln |\sec x + \tan x|$$

$$= -\cos x \ln |\sec x + \tan x|$$

Therefore, the general solution is:

$$y = C_1 \cos x + C_2 \sin x - \cos x \ln |\sec x + \tan x|$$

H.W.

1. Solve: $y'' - y = e^x$ [Ans: $y_p(x) = x e^x / 2 - e^x / 4$]

2. $y'' + y = \sec x$ [Ans: $y_p(x) = x \sin x + \cos x \ln |\cos x|$]

3. $t y'' - (1+t) y' + y = t^2 e^{2t}$ [Ans: $y_p(t) = \frac{t+1}{2} e^{2t}$]

4. $y'' = x^3$

5. $y'' + y' = \ln|x|$

6. $y'' - 2y' + y = e^x$